Power to the People: The Role of Humans in Interactive Machine Learning

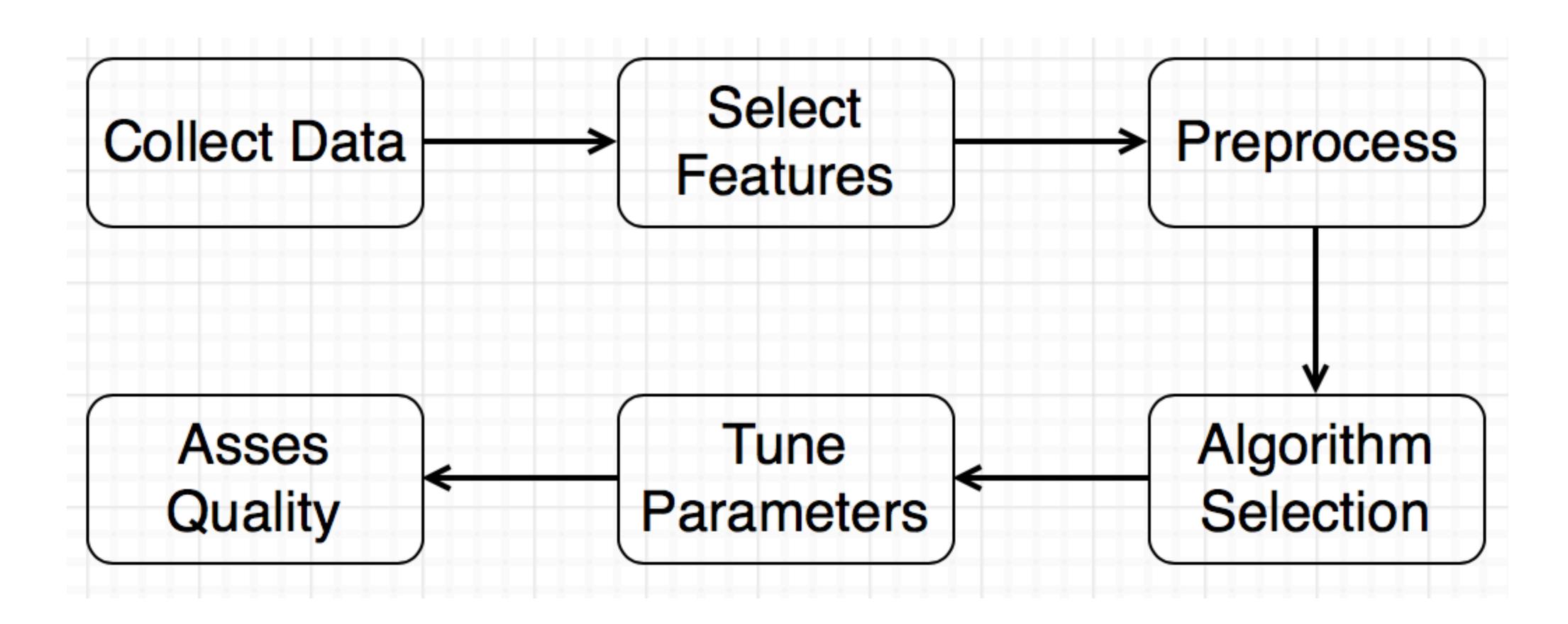
S Amershi, M Cakmak, WB Knox, T Kulesza

Presented by

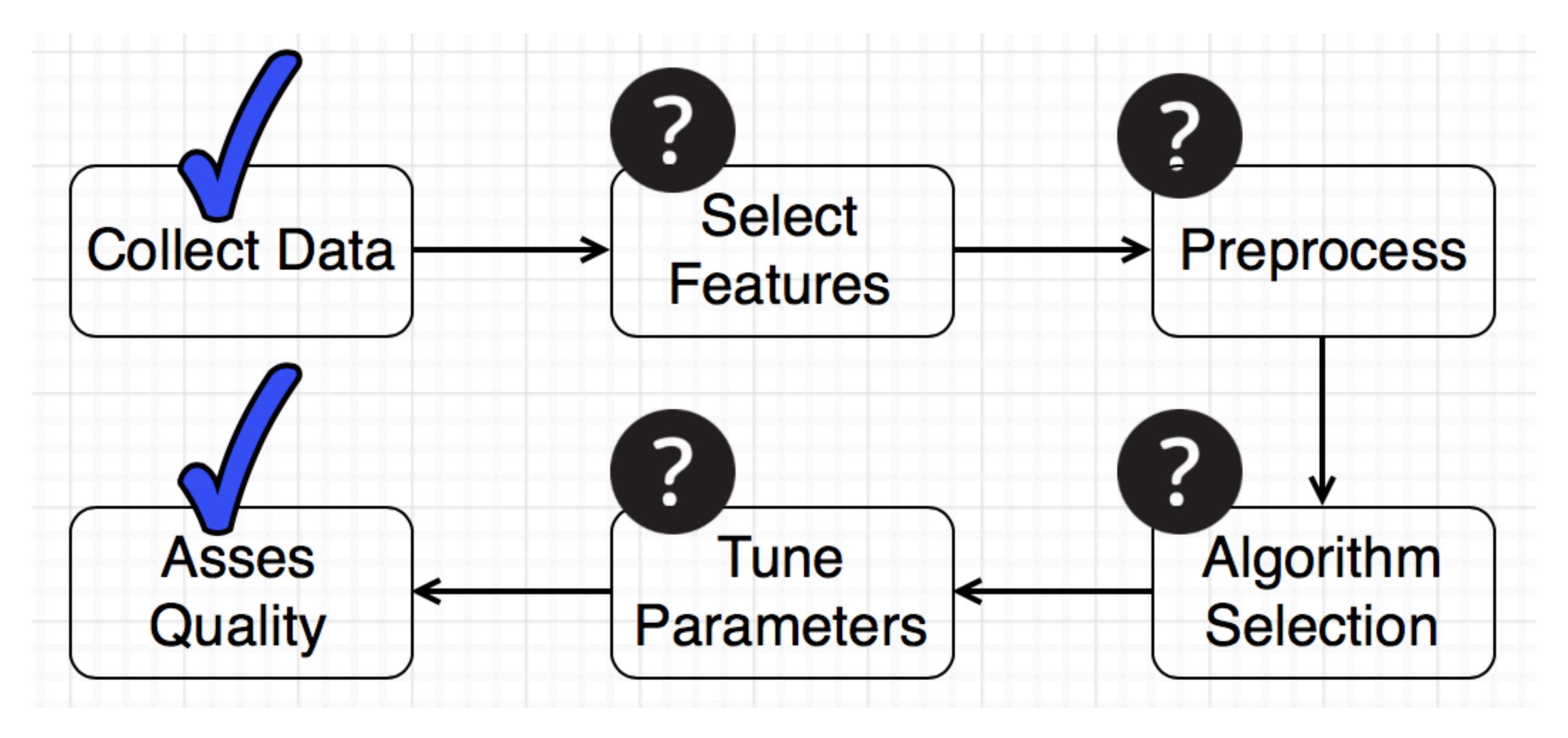
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November 23rd 2016

A Typical Approach to ML



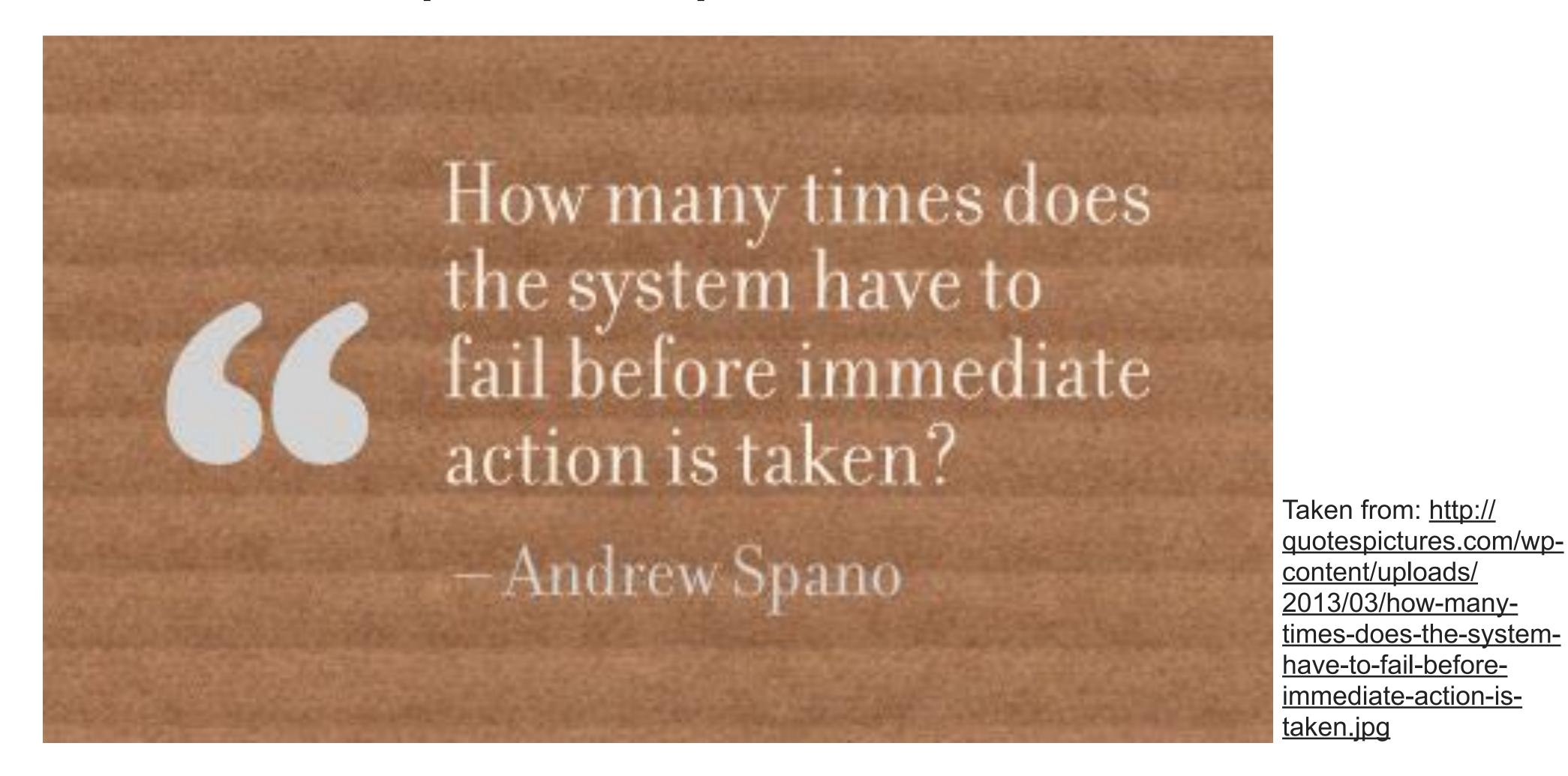
How End Users See the Process



Interactive Machine Learning

- Rapid, Focused, and Incremental!
- Allows users to explores the model space visually and interactively
- Reduces the need of supervision by ML experts
- Intelligent user interfaces and iML have been around for a over a decade (Hook 2000, Cohn 2003)

Rapid Updates



Focused



Taken from: http://gym.westernsydney
.edu.au/wp-
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2016/10/
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SmallSteps-01.png
SmallSteps-01.png

Incremental



Taken from: https://cdn.shopify.com/s/files/1/0070/7032/files/The_10_Strategy.jpg?754

Discussion

- iML results in a tight coupling which leads to cross influence
- Studying user interaction can challenge assumptions of traditional learning systems
- End user interaction can be expanded into same aspects as of ML experts

Discussion Outline

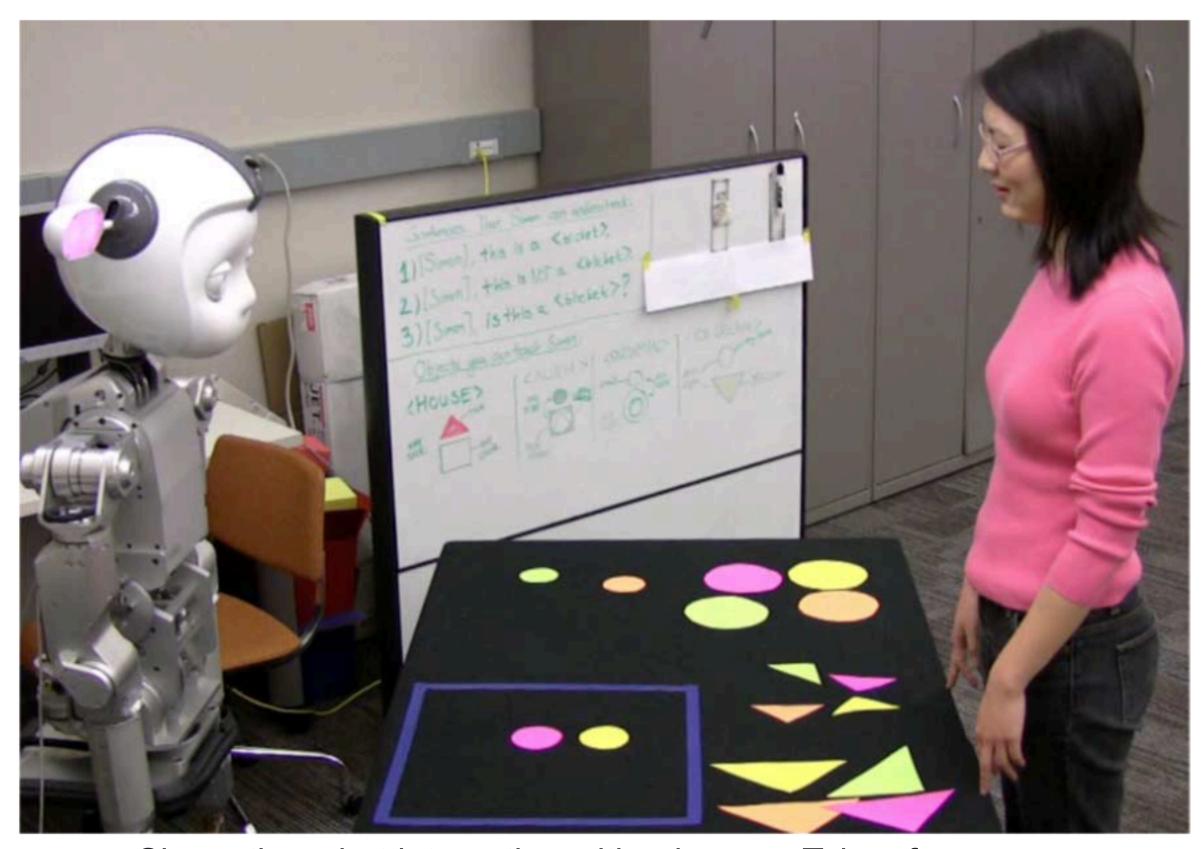
- 1. User Interaction with iML
- 2. Interfaces for iML
- 3. Challenges in iML

User Interaction with iML

- People vs oracles
- Positive vs negative feedback
- People want to demonstrate how learners should behave
- People want to provide more than just data Labels
- People value transparency in learning systems
- Transparency can improve label quality

People vs Oracles

- Cakmak (2010): Pairs a robot with a person using three types of interaction
- Found people tend to underestimate the performance of Simon
- Found people want to control how the robots interaction



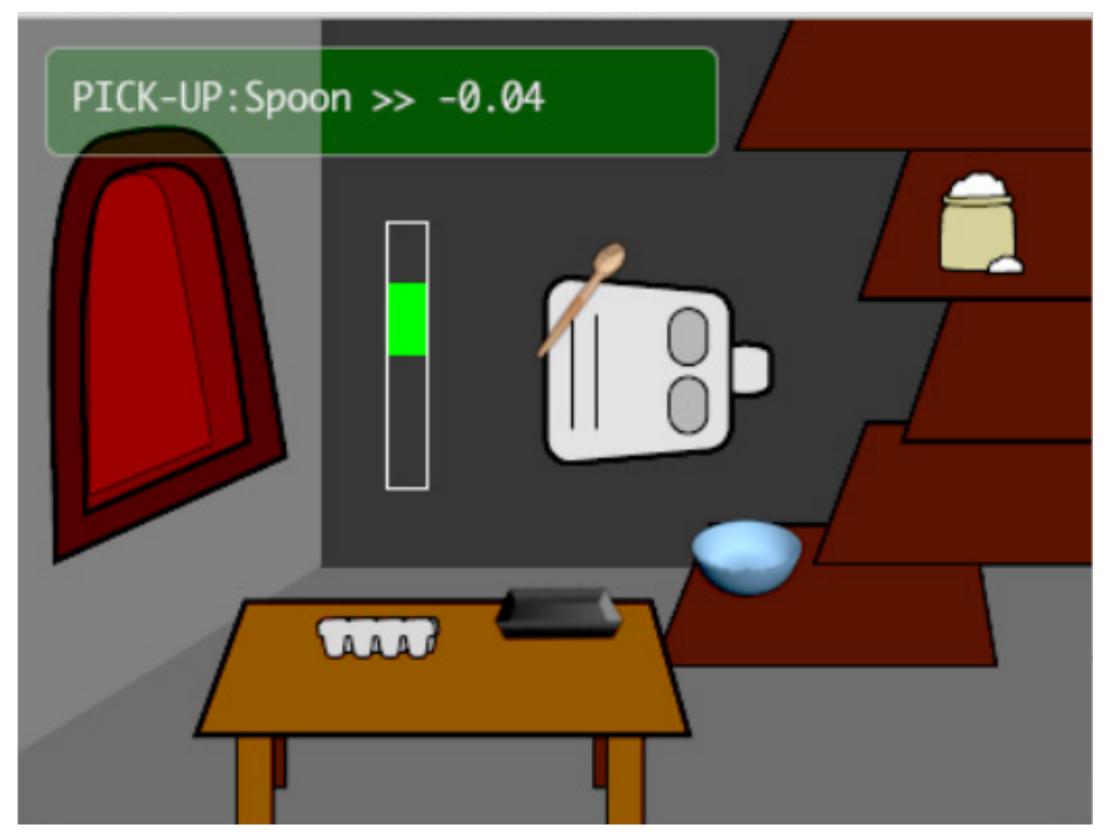
Simon the robot interacting with a human. Taken from: Cakmak, M., Chao, C., & Thomaz, A. L. 2010. Designing interactions for robot active learners. *Autonomous Mental Development, IEEE Transactions on*, *2*(2), 108-118.

Positive vs Negative Feedback

- Thomaz + Breazeal (2008): Found people tend to give more positive feedback than negative feedback in episodic tasks
- Myopic algorithms don't work well with this
- Knox + Stone (2013): Created VI Tamer using MDP. First to learn successfully non myopically from human generate reward!

Demonstrating how Learners Should Behave

- Thomaz + Breazeal (2008): Find people often violate rules of interaction with robots
- Human interaction can change the overall goal of learners



Sophie's Kitchen MDP. From: Thomaz, A. L., & Breazeal, C. 2008. Teachable robots: Understanding human teaching behavior to build more effective robot learners. *Artificial Intelligence*, *172*(6), 716-737.

Providing more than just Data Labels

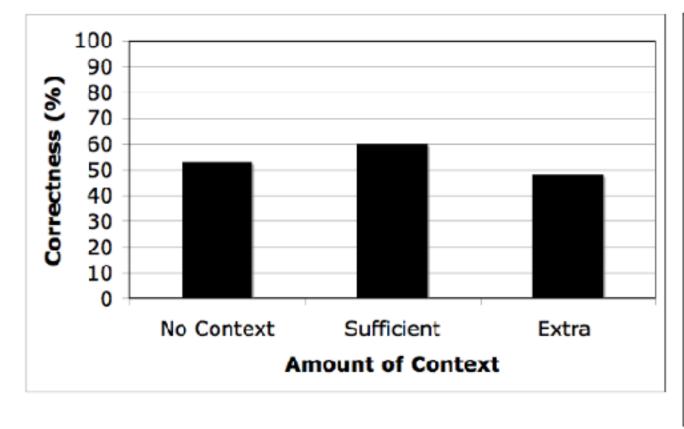
- Stumpf (2007): Designed a text classification system and allowed people to provide feedback based on explanations of the system
- Showed humans want/like to provide feedback
- Can you think of other ways humans can help the ML process?

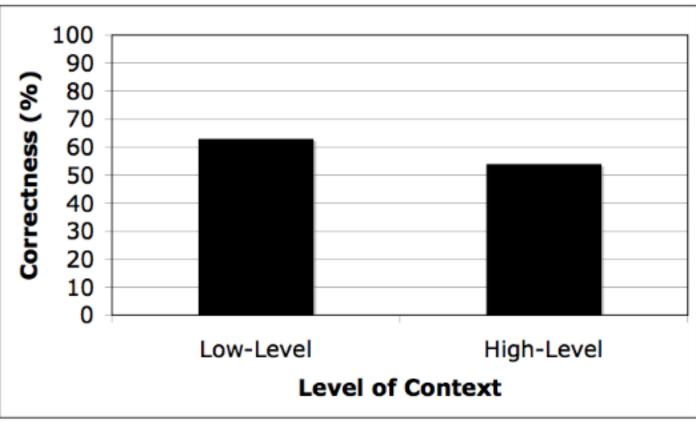
Valuing Transparency

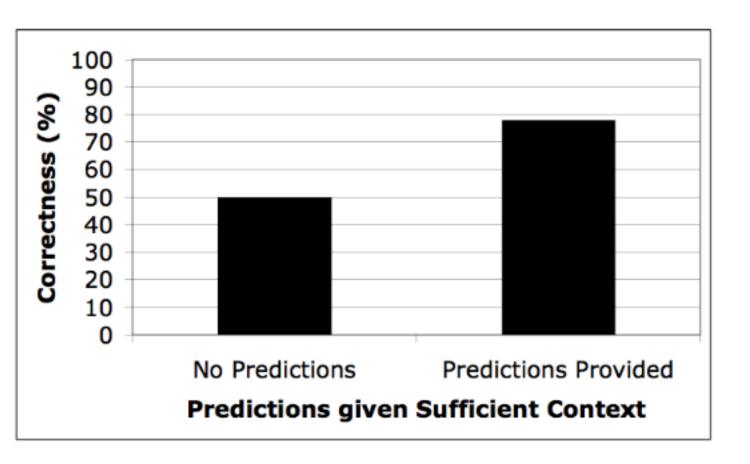
- Kulesza (2012): Explained to a group of user how a music app's recommender works and how user feedback in the app is used
- Found humans that had the explanation provided better feedback and were more satisfied with the app

Improving Label Quality

- Rosenthal (2010): Studied how five additional features that may assist label processes
- Found that with sufficient context and prediction of answer, humans can provide better labels







Taken from: Rosenthal, S. L., & Dey, A. K. 2010. Towards maximizing the accuracy of human-labeled sensor data. In *Proceedings of the 15th international conference on Intelligent user interfaces* (pp. 259- 268). ACM.

Interfaces with iML

- Supporting assessment of model quality
- Supporting experimentation with model inputs
- Appropriately timing queries
- Enabling users to query the learner
- Enabling users to critique learner output
- Allowing users to specify preferences on errors
- Combining Models

Supporting Assessment of Model Quality

- Forgart (2010): created CueFlik which allows users to view information from both classes
- Amershi (2009): Found the best way is to show users high value examples with model summary helps users train better models

Supporting Experimentation with Model Input

- What if you did not have a backspace button on your keyboard?
- Amershi (2010): Expanded CueFlik to include an undo button with visualizations of user history
- Found users were able to create better models in the same amount of time
- Users are not perfect; users have expectations

Appropriately Timing Queries

- How do you ask a question? How would Simon do it?
- Users preferred teacher triggered queries => more control
- Economics of utility play an interesting role in human utilization

Enabling Users to Query the Learner

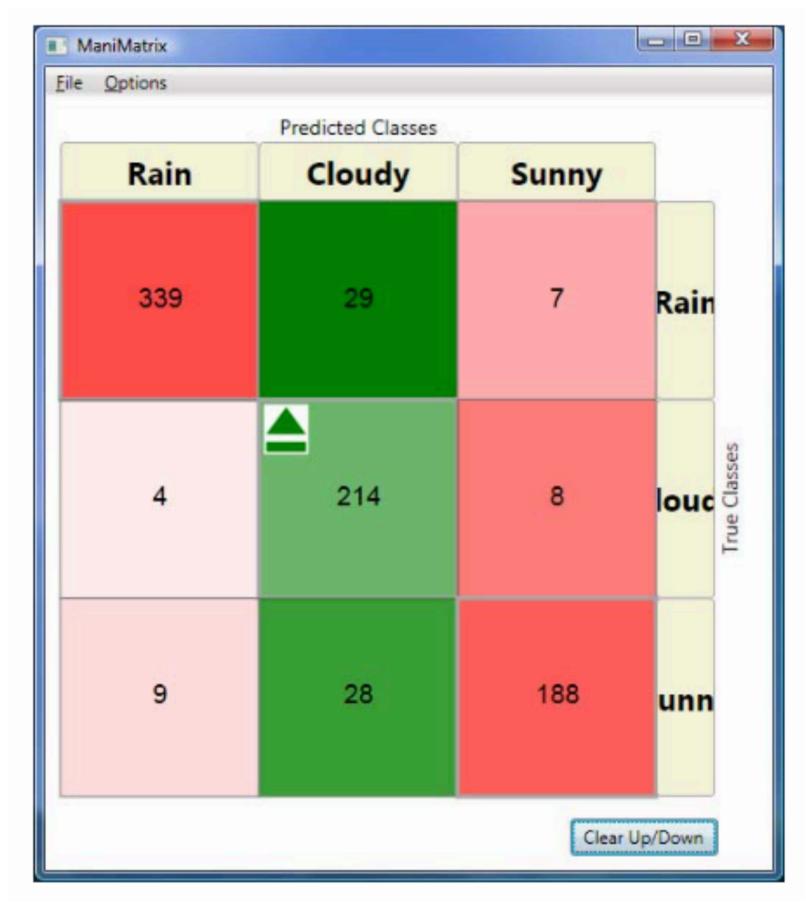
- Kulesza (2011): created a text classifier that would display statistics on features to a user, allowing a user to adjust features
- How can iML explain itself effectively for a user to provide feedback?

Enabling Critique of Learner Output

- Vig (2011): studied this interaction using MovieLens to find similar items using KNN
- 89% of users liked the tool! 79% wanted it to become a permanent feature
- User attitude toward a learner can change when they are given interactive control

Allowing Users to Specify Preferences

- Precision, accuracy, recall. Which is more important?
- Kapoor (2010) created ManiMatrix allowing users to interactively adjust decision boundaries using the confusion matrix
- Allows non experts to change iML performance based on their needs



Taken from: Kapoor, A., Lee, B., Tan, D., & Horvitz, E. 2010. Interactive optimization for steering machine classification. In *Proceedings of the SIGCHI Conference on Human Factors in Computing Systems* (pp. 1343-1352). ACM.

Combining Models

- How many ensemble methods are there?
- Talbot (2009): created EnsembleMatrix allowing users to interactively engage with multiple methods
- Allows visualization of building a model, evaluating, and exploring effects
- Combining human intuition with ML allowing users to create better classifiers faster!

Challenges in iML

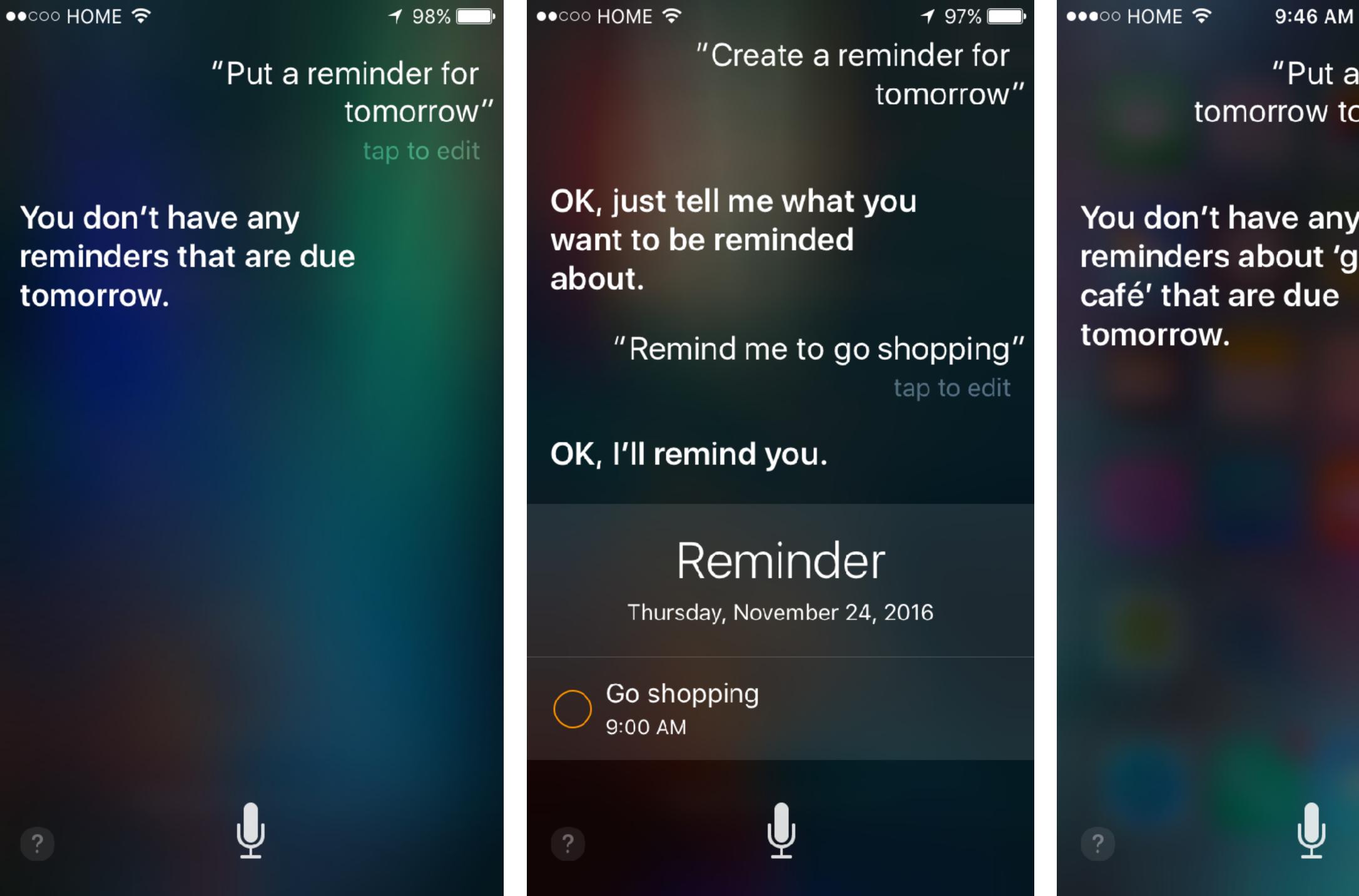
- Common languages across diverse fields
- principles and guidelines for how to design human interaction with ML
- Techniques and standards for evaluating iML systems
- Leveraging the masses
- Algorithmic problems in iML
- Collaboration across the fields of HCI and ML

Common Languages

- What is iML? Relevance feedback? Socially guided ML? PBD?
- Impeding awareness and possibility of duplicate work
- Researchers need to look across diverse fields
- Porter (2013): breaks iML into 3 dimensions:
 - Task Decomposition
 - Training Vocabulary
 - Training Dialog

Principles and Guidlines

- iML systems do not always follow the principles of understandability and actionability
- Proposed guidelines include: safety and trust, managing expectations of users, and helping to avoid user frustration
- Experience in developing iML systems ...
- Extracting and evaluating dimensions from research ...



"Put a reminder for tomorrow to go to a café"

→ \$ 94% **□**

tap to edit

You don't have any reminders about 'go to a

Evaluating iML Systems

- What does it mean for an iML system to fail? or succeed?
- How can we gauge effectiveness?
- Avoid generalizations of specific interaction techniques and instead generalize situations and contexts

Leveraging the Masses

- How can iML scale up from one user?
- Create systems that can integrate more users (Crowdsourcing ??)
- Are iML systems reusable? combinable? generalizable?
- iML needs Coordination!

Algorithmic Problems in iML

- What's more important: speed or accuracy?
- Do current iML algorithms allow natural interaction with users?

Collaboration in HCI with ML

- HCI: Human Computer Interaction
- HCI can help in evaluating iML systems with potential users
- Leveraging both solutions!

Examples of iML

- https://www.youtube.com/watch?v=JL-M-1utrlY
- https://vimeo.com/76664145

Conclusion

- You should have idea of what iML is and why it's awesome!
- You should understand the need of exploring user interaction with ML
- You should agree that there are many ways in which iML can harness human power and combine it with ML power
- iML will lead to more capable ML models and more capable end users

Suggested Resources

- https://www.youtube.com/user/SimonTheSocialRobot/videos
- https://www.youtube.com/watch?v=-2ggKevM-_8

- Amershi, S., Fogarty, J., Kapoor, A. and Tan, D. 2009. Overview-Based Example
 Selection in Mixed-Initiative Concept Learning. In Proceedings of the ACM Symposium
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- Amershi, S., Fogarty, J., Kapoor, A. and Tan, D. 2010. Examining Multiple Potential
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- Knox, W. B., & Stone, P. 2013. Learning non-myopically from human-generated reward.
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- Kulesza, T., Stumpf, S., Wong, W. K., Burnett, M. M., Perona, S., Ko, A., & Oberst, I. 2011. Why-oriented end-user debugging of naive Bayes text classification. ACM Transactions on Interactive Intelligent Systems (TiiS), 1(1), 2.

- Kulesza, T., Stumpf, S., Burnett, M., & Kwan, I. 2012. Tell me more?: the effects of mental model soundness on personalizing an intelligent agent. In Proceedings of the SIGCHI Conference on Human Factors in Computing Systems (pp. 1-10). ACM.
- Porter, R., Theiler, J., & Hush, D. 2013. Interactive Machine Learning in Data Exploitation. Technical Report. Los Alamos National Lab.
- Rashid, A. M., Ling, K., Tassone, R. D., Resnick, P., Kraut, R., & Riedl, J. 2006. Motivating participation by displaying the value of contribution. In Proceedings of the SIGCHI conference on Human Factors in computing systems (pp. 955-958). ACM.
- Rosenthal, S. L., & Dey, A. K. 2010. Towards maximizing the accuracy of human-labeled sensor data. In Proceedings of the 15th international conference on Intelligent user interfaces (pp. 259- 268). ACM.

- Stumpf, S., Rajaram, V., Li, L., Burnett, M., Dietterich, T., Sullivan, E., Drummond, R., & Herlocker, J. 2007. Toward harnessing user feedback for machine learning. In Proceedings of the 12th international conference on Intelligent user interfaces (pp. 82-91). ACM.
- Talbot, J., Lee, B., Kapoor, A., & Tan, D. S. 2009. EnsembleMatrix: interactive visualization to support machine learning with multiple classifiers. In Proceedings of the 27th international conference on Human factors in computing systems (pp. 1283-1292). ACM.
- Thomaz, A. L., & Breazeal, C. 2008. Teachable robots: Understanding human teaching behavior to build more effective robot learners. Artificial Intelligence, 172(6), 716-737.
- Vig, J., Sen, S., & Riedl, J. 2011. Navigating the tag genome. In Proceedings of the 16th international conference on Intelligent user interfaces (pp. 93-102). ACM.

Thank You!